Modelchecking Non-Functional Requirements for Interface Specifications

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Software Ubiquitous in Safety Critical Systems



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Importance of Specification and Verification of rich Interfaces

Our Approach: Requirements Feedback Loop

- Feedback loop between requirements and design phases
 - 1 Requirements: Object-Z specification M (functional), Temporal Logic formulas ρ (non-functional)
 - **2** Translate to SMV: $\phi(M), \phi(\rho)$
 - **3** Modelcheck result (Consistency and $\phi(M) \vdash \phi(\rho)$)
 - Use feedback for improvement of requirements and iterate

Overview



- 2 Translation from Object-Z to SMV
- 3 Case Study TWIN-Elevator
- 4 Feedback Loop: Example



Specification in Object-Z

- Extension of specification language Z by objects:
 - OO-features: Classes, objects
 - Interfaces (by visibility lists)
 - Inheritance, polymorphism
- Formal specification of Interfaces in a very general way
- Full predicate calculus available to specify invariants and operations
- ⇒ Rich interfaces (for functional requirements) can be explicitly specified
- Non-functional requirements integrated through temporal logic and feedback loop

SMV Modelchecking



ACM Turing Award Honors Founders of Automatic Verification Technology Researchers Created Model Checking Technique for

Hardware and Software Designers

- SMV is a classical Modelchecker for CTL and LTL
- SMV's input language similar to programming language (Verilog style)
- Supports simple datatypes and modules

Translation from Object-Z to SMV

- Profit from syntactic similarities
 - ⇒ Translation identifies: types(bool), constants, classes, instantiation
- Watch out for semantical differences
 - ⇒ Special: state transition, operations, operation composition



 \Rightarrow SMV: "redefining var"

Special Translation for Operations: Stimulus

In O-Z operations are offered, must be invoked by environment Additional variable mimicks operation stimulus explicitly in SMV

```
next(var) := case {
   plus_stimulus & plus_pre : var + 1;
   minus_stimulus & minus_pre : var - 1;
   default: var; };
```

Translation from Object-Z to SMV

- Translation Soundness
 - Translation is a homomorphism ϕ of the boolean lattices of Object-Z and SMV
 - State change preserves φ: both formalism contain logical representation of "change"
 - In Object-Z: pre-state s, post-state s'
 - In SMV: pre-state s, post-state next s



- Translation not complete:
 - · Quantification only for finite domains
 - OO notion of self not supported by SMV modules
- ... but sufficiently practical

The TWIN Problem and ThyssenKrupp Solution





Feedback Loop: Example from TWIN



 Example requirement: cabin's movements are restricted by boundaries shaft:

```
LevelGround ≤system.curr_level  LevelTop
```

Translation into SMV:

```
CabinStaysInShaft: assert
   G (LevelGround <= system.curr_level)
   & (system.curr_level <= LevelTop);
[cont'd]</pre>
```

Feedback Loop: Example from TWIN [cont'd]

SMV detects violation of safety requirement:

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- Operation MoveUp responsible for illegal change of curr_level
- ⇒ Add precondition curr_level < LevelTop</p>

Results of the Case Study

- All safety properties of TWIN system could be successfully verified
- Observations:
- Feedback loop enables detection of inconsistencies
- Specification is abstract description of interfaces reducing to behaviour relevant for safety, e.g. DSC



actual implementation of cabin selection is irrelevant
 ⇒ this part of the behaviour is *not* part of interface

Summary and Lessons Learned

Summary:

- Interface specification with Object-Z
- Feedback loop to requirements for quality:
 - Translation to SMV
 - Modelcheck specification
- Case study TWIN-elevator shows feasibility
- Object-Z: formal specification "traditional way"
 - Stepwise, iterated specification refinement
 - Elegant and abstract (in comparison to SMV)
 - Temporal logic together with Object-Z seems natural
 - Pragmatism of translation; so far no restriction